

# Advanced Compiler Construction Theory And Practice



Introduction to loop dependence  
and Optimizations

# A little about myself

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## **Research Interests**

- Compiler construction, software productivity
- program analysis and optimization for high-performance computing
- Parallel programming

## **Overall goal: develop tools to improve the productivity and efficiency of programming**

- Optimizing compilers for high performance computing
- Programmable optimization and tuning of Scientific codes

# General Information

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- Reference books
  - Optimizing Compilers for Modern Architectures: A Dependence-based Approach,
    - Randy Allen and Ken Kennedy, Morgan-Kaufman Publishers Inc.
  - Book Chapter: Optimizing And Tuning Scientific Codes
    - Qing Yi. SCALABLE COMPUTING AND COMMUNICATIONS:THEORY AND PRACTICE.
    - <http://www.cs.uccs.edu/~qyi/papers/BookChapter11.pdf>
  - Structured Parallel Programming Patterns for Efficient Computation
    - Michael McCool, James Reinders, and Arch Robison. Morgan Kaufmann. 2012.
    - [http://parallelbook.com/sites/parallelbook.com/files/SC13\\_20131117\\_Intel\\_McCool\\_Robison\\_Reinders\\_Hebenstreit.pdf](http://parallelbook.com/sites/parallelbook.com/files/SC13_20131117_Intel_McCool_Robison_Reinders_Hebenstreit.pdf)
- Course materials
  - <http://www.cs.uccs.edu/~qyi/classes/Dragonstar>
- The POET project web site:
  - <http://www.cs.uccs.edu/~qyi/poet/index.php>

# High Performance Computing

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- Applications must efficiently manage architectural components
  - Parallel processing
    - Multiple execution units --- pipelined
    - Vector operations, multi-core
    - Multi-tasking, multi-threading (SIMD), and message-passing
  - Data management
    - Registers
    - Cache hierarchy
    - Shared and distributed memory
  - Combinations of the above
  
- What are the compilation challenges?

# Optimizing For High Performance

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- Goal: eliminating inefficiencies in programs
- Eliminating redundancy: if an operation has already been evaluated, don't do it again
  - Especially if the operation is inside loops or part of a recursive evaluation
  - All optimizing compilers apply redundancy elimination,
    - e.g., loop invariant code motion, value numbering, global RE
- Resource management: reorder operations and/or data to better map to the targeting machine
  - Reorder computation(operations)
    - parallelization, vectorization, pipelining, VLIW, memory reuse
    - Instruction scheduling and loop transformations
  - Re-organization of data
    - Register allocation, regrouping of arrays and data structures

# Optimizing For Modern Architectures

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- Key: reorder operations to better manage resources
  - Parallelization and vectorization
  - memory hierarchy management
  - Instruction and task/threads scheduling
  - Interprocedural (whole-program) optimizations
- Most compilers focus on optimizing loops, why?
  - This is where the application spends most of its computing time
  - What about recursive function/procedural calls?
    - Extremely important, but often left unoptimized...

# Compiler Technologies

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- Source-level optimizations
  - Most architectural issues can be dealt with by restructuring the program source
    - Vectorization, parallelization, data locality enhancement
  - Challenges:
    - Determining when optimizations are legal
    - Selecting optimizations based on profitability
- Assembly level optimizations
  - Some issues must be dealt with at a lower level
    - Prefetch insertion
    - Instruction scheduling
- All require some understanding of the ways that instructions and statements depend on one another (share data)

# Syllabus

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- Dependence Theory and Practice
  - Automatic detection of parallelism.
  - Types of dependences; Testing for dependence;
- Memory Hierarchy Management
  - Locality enhancement; data layout management;
  - Loop interchange, blocking, unroll&jam, unrolling,...
- Loop Parallelization
  - More loop optimizations: OMP parallelization, skewing, fusion, ...
  - Private and reduction variables
- Pattern-driven optimization
  - Structured Parallelization Patterns
  - Pattern-driven composition of optimizations
- Programmable optimization and tuning
  - Using POET to write your own optimizations



# Dependence-based Optimization

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## □ **Bernstein's Conditions**

- **it is safe to run two tasks R1 and R2 in parallel if none of the following holds:**
  - **R1 writes into a memory location that R2 reads**
  - **R2 writes into a memory location that R1 reads**
  - **Both R1 and R2 write to the same memory location**

- There is a dependence between two statements if
  - They might access the same location,
  - There is a path from one to the other, and
  - One of the accesses is a write
- Dependence can be used for
  - Automatic parallelization
  - Memory hierarchy management (registers and caches)
  - Scheduling of instructions and tasks

# Dependence - Static Program Analysis

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- Program analysis --- support software development and maintenance
  - Compilation --- identify errors without running program
    - Smart development environment (check simple errors as you type)
  - Optimization --- cannot not change program meaning
    - Improve performance, efficiency of resource utilization
    - Code revision/re-factoring ==> reusability, maintainability,
  - Program correctness --- Is the program safe/correct?
    - Program verification -- Is the implementation safe, secure?
    - Program integration --- are there any communication errors?
- In contrast, if the program needs to be run to figure out information, it is called dynamic program analysis.

# Data Dependences

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- **There is a data dependence from statement  $S_1$  to  $S_2$  if**
  1. **Both statements access the same memory location,**
  2. **At least one of them stores onto it, and**
  3. **There is a feasible run-time execution path from  $S_1$  to  $S_2$**
- Classification of data dependence
  - True dependences (Read After Write hazard)  
 $S_2$  depends on  $S_1$  is denoted by  $S_1 \delta S_2$
  - Anti dependence (Write After Read hazard)  
 $S_2$  depends on  $S_1$  is denoted by  $S_1 \delta^{-1} S_2$
  - Output dependence (Write After Write hazard)  
 $S_2$  depends on  $S_1$  is denoted by  $S_1 \delta^0 S_2$
- Simple example of data dependence:  
 $S_1$  PI = 3.14  
 $S_2$  R = 5.0  
 $S_3$  AREA = PI \* R \*\* 2

# Transformations

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- A reordering Transformation
  - Changes the execution order of the code, without adding or deleting any operations.
- Properties of Reordering Transformations
  - It does not eliminate dependences, but can change the ordering (relative source and sink) of a dependence
  - If a dependence is reverted by a reordering transformation, it may lead to incorrect behavior
- A reordering transformation is safe if it preserves the relative direction (i.e., the source and sink) of each dependence.

# Dependence in Loops

```
DO I = 1, N
S1  A(I+1) = A(I) + B(I)
ENDDO
```

```
DO I = 1, N
S1  A(I+2) = A(I) + B(I)
ENDDO
```

- In both cases, statement S1 depends on itself
  - However, there is a significant difference
- We need to distinguish different iterations of loops
  - The iteration number of a loop is equal to the value of the loop index (loop induction variable)
  - Example:

```
DO I = 0, 10, 2
S1  <some statement>
ENDDO
```
- What about nested loops?
  - Need to consider the nesting level of a loop

# Iteration Vectors

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- Given a nest of  $n$  loops, iteration vector  $i$  is
  - A vector of integers  $\{i_1, i_2, \dots, i_n\}$   
where  $i_k, 1 \leq k \leq n$  represents the iteration number for the loop at nesting level  $k$

- Example:

```
DO I = 1, 2
  DO J = 1, 2
    S1      <some statement>
  ENDDO
ENDDO
```

- The iteration vector  $(2, 1)$  denotes the instance of  $S_1$  executed during the 2nd iteration of the I loop and the 1st iteration of the J loop

# Loop Iteration Space

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- For each loop nest, its iteration space is
  - The set of all possible iteration vectors for a statement
  - Example:

```
DO I = 1, 2  
  DO J = 1, 2  
    S1    <some statement>  
  ENDDO  
ENDDO
```

The iteration space for S1 is  $\{ (1,1), (1,2), (2,1), (2,2) \}$

# Ordering of Iterations

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- Within a single loop iteration space,
  - We can impose a lexicographic ordering among its iteration Vectors
- Iterations  $i$  precedes  $j$ , denoted  $i < j$ , iff
  - Iteration  $i$  is evaluated before  $j$
  - That is, for some nesting level  $k$ 
    1.  $i[i:k-1] < j[1:k-1]$ , or
    2.  $i[1:k-1] = j[1:k-1]$  and  $i_n < j_n$
  - Example:  $(1,1) < (1,2) < (2,1) < (2,2)$



# Loop Dependence

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There exists a dependence from statement S1 to S2 in a common nest of loops if and only if

- there exist two iteration vectors  $i$  and  $j$  for the nest, such that
  - (1)  $i < j$  or  $i = j$  and there is a path from S1 to S2 in the body of the loop,
  - (2) statement S1 accesses memory location M on iteration  $i$  and statement S2 accesses location M on iteration  $j$ , and
  - (3) one of these accesses is a write.

# Distance and Direction Vectors

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- Consider a dependence in a loop nest of  $n$  loops
  - Statement  $S1$  on iteration  $i$  is the source of dependence
  - Statement  $S2$  on iteration  $j$  is the sink of dependence
- The distance vector is a vector of length  $n$   $d(i,j)$  such that:  
 $d(i,j)_k = j_k - I_k$
- The direction Vector is a vector of length  $n$   $D(i,j)$  such that  
(Definition 2.10 in the book)

$$D(i,j)_k = \begin{cases} "<" & \text{if } d(i,j)_k > 0 \\ "=" & \text{if } d(i,j)_k = 0 \\ ">" & \text{if } d(i,j)_k < 0 \end{cases}$$

- What is the dependence distance/direction vector?

```
DO I = 1, N
  DO J = 1, M
    DO K = 1, L
      S1    A(I+1, J, K-1) = A(I, J, K) + 10
```

# Loop-carried and Loop-independent Dependences

- If in a loop statement S2 on iteration  $j$  depends on S1 on iteration  $i$ , the dependence is
  - **Loop-carried** if either of the following conditions is satisfied
    - S1 and S2 execute on different iterations i.e.,  $i \neq j$
    - $d(i,j) > \mathbf{0}$  i.e.  $D(i,j)$  contains a "<" as leftmost non "=" component
  - **Loop-independent** if either of the conditions is satisfied
    - S1 and S2 execute on the same iteration i.e.,  $i=j$
    - $d(i,j) = \mathbf{0}$ , i.e.  $D(i,j)$  contains only "=" component
    - NOTE: there must be a path from S1 to S2 in the same iteration
- Example:

```
DO I = 1, N
S1      A(I+1) = F(I) + A(I)
S2      F(I) = A(I+1)
ENDDO
```

# Level of loop dependence

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- The level of a loop-carried dependence is the index of the leftmost non-“=” of  $D(i,j)$ 
  - A level- $k$  dependence from  $S_1$  to  $S_2$  is denoted  $S_1 \delta_k S_2$
  - A loop independent dependence from  $S_1$  to  $S_2$  is denoted  $S_1 \delta_\infty S_2$
- Example:

```
DO I = 1, 10
  DO J = 1, 10
    DO K = 1, 10
      S1      A(I, J, K+1) = A(I, J, K)
      S2      F(I, J, K) = A(I, J, K+1)
    ENDDO
  ENDDO
ENDDO
```

# Loop Optimizations

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- A loop optimization may
  - Change the order of iterating the iteration space of each statement
  - Without altering the direction of any original dependence
- Example loop transformations
  - Change the nesting order of loops
  - Fuse multiple loops into one or split one into multiple
  - Change the enumeration order of each loop
  - And more ...
- Any loop reordering transformation that
  - (1) does not alter the relative nesting order of loops and
  - (2) preserves the iteration order of the level-k looppreserves all level-k dependences.

# Dependence Testing

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```
DO i1 = L1, U1, S1
  DO i2 = L2, U2, S2
    ...
    DO in = Ln, Un, Sn
      S1  A(f1(i1,...,in),...,fm(i1,...,in)) = ...
      S2  ... = A(g1(i1,...,in),...,gm(i1,...,in))
    ENDDO
  ENDDO
ENDDO
```

- A dependence exists from S1 to S2 iff there exist iteration vectors  $x=(x_1,x_2,\dots,x_n)$  and  $y=(y_1,y_2,\dots,y_n)$  such that
  - (1)  $x$  is lexicographically less than or equal to  $y$ ;
  - (2) the system of **diophantine equations** has an integer solution:
$$f_i(x) = g_i(y) \text{ for all } 1 \leq i \leq m$$
i.e.  $f_i(x_1,\dots,x_n)-g_i(y_1,\dots,y_n)=0$  for all  $1 \leq i \leq m$

# Example

---

```
DO I = 1, 10
  DO J = 1, 10
    DO K = 1, 10
      S1      A(I, J, K+1) = A(I, J, K)
      S2      F(I, J, K) = A(I, J, K+1)
    ENDDO
  ENDDO
ENDDO
```

- To determine the dependence between  $A(I, J, K+1)$  at iteration vector  $(I_1, J_1, K_1)$  and  $A(I, J, K)$  at iteration vector  $(I_2, J_2, K_2)$ , solve the system of equations
  - $I_1 = I_2; J_1 = J_2; K_1 + 1 = K_2; 1 \leq I_1, I_2, J_1, J_2, K_1, K_2 \leq 10$
  - Distance vector is  $(I_2 - I_1, J_2 - J_1, K_2 - K_1) = (0, 0, 1)$
  - Direction vector is  $(=, =, <)$
  - The dependence is from  $A(I, J, K+1)$  to  $A(I, J, K)$  and is a true dependence

# The Delta Notation

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- Goal: compute iteration distance between the source and sink of a dependence

```
DO I = 1, N
  A(I + 1) = A(I) + B
ENDDO
```

- Iteration at source/sink denoted by:  $I_0$  and  $I_0 + \Delta I$
- Forming an equality gets us:  $I_0 + 1 = I_0 + \Delta I$
- Solving this gives us:  $\Delta I = 1$
- If a loop index does not appear, its distance is \*

- \* means the union of all three directions  $<, >, =$

```
DO I = 1, 100
DO J = 1, 100
  A(I+1) = A(I) + B(J)
```

- The direction vector for the dependence is  $(<, *)$



# Complexity of Testing

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- Find integer solutions to a system of Diophantine Equations is NP-Complete
  - Most methods consider only linear subscript expressions
- Conservative Testing
  - Try to prove absence of solutions for the dependence equations
  - Conservative, but never incorrect
- Categorizing subscript testing equations
  - ZIV if it contains no loop index variable
  - SIV if it contains only one loop index variable
  - MIV if it contains more than one loop index variables

$$A(5, I+1, j) = A(1, I, k) + C$$

5=1 is ZIV; I1+1=I2 is SIV; J1=K2 is MIV

# Summary

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- Introducing data dependence
  - What is the meaning of S2 depends on S1?
  - What is the meaning of  $S_1 \delta S_2$ ,  $S_1 \delta^{-1} S_2$ ,  $S_1 \delta^0 S_2$ ?
  - What is the safety constraint of reordering transformations?
- Loop dependence
  - What is the meaning of iteration vector (3,5,7)?
  - What is the iteration space of a loop nest?
  - What is the meaning of iteration vector  $I < J$ ?
  - What is the distance/direction vector of a loop dependence?
  - What is the relation between dependence distance and direction?
  - What is the safety constraint of loop reordering transformations?
- Level of loop dependence and transformations
  - What is the meaning of loop carried/independent dependences?
  - What is the level of a loop dependence or loop transformation?
  - What is the safety constraint of loop parallelization?
- Dependence testing theory