

Exercise 3: Exploring Parallelism

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1. What are the different ways of exploring parallelism?

2. What is the granularity of a parallelized computation? How to control it using loop optimizations?

3. What is the safety constraint of loop parallelization?

4. What is a private variable?

5. What is a reduction variable?

6. How can each of the following optimizations be used to control the granularity of parallelism of a program??
 - (a) Loop parallelization via OpenMP parallel for
 - (b) Loop vectorization via SIMD vector registers
 - (c) Loop pipelining
 - (d) Loop strip-mining
 - (e) Loop interchange
 - (f) Loop fusion
 - (g) Loop skewing

Try parallelize each of the following code fragments via combinations of loop optimizations.

- ```
1. void dgemm(double *a,double *b,
 double *c, double beta, int n)
{
 int i,j,k;
 for (j = 0; j < n; j ++)
 for (i = 0; i < n; i ++)
 c[j*n+i] = beta*c[j*n+i];
 for (k = 0; k < n; k ++)
 for (j = 0; j < n; j ++)
 for (i = 0; i < n; i ++)
 c[j*n+i] +=
 a[k*n+i] * b[j*n+k];
}
```
- ```
2. DO J = 1, JMAXD
    DO I = 1, IMAXD
        F(I, J, 1) = F(I, J, 1) * B(1)
    DO K = 2, N-1
        DO J = 1, JMAXD
            DO I = 1, IMAXD
                F(I,J,K)=(F(I,J,K) - A(K)*F(I,J,K-1))*B(K)
    DO J = 1, JMAXD
        DO I = 1, IMAXD
            TOT(I, J) = 0.0
    DO J = 1, JMAXD
        DO I = 1, IMAXD
            TOT(I, J) = TOT(I, J) + D(1) * F(I, J, 1)
    DO K = 2, N-1
        DO J = 1, JMAXD
            DO I = 1, IMAXD
                TOT(I, J) = TOT(I, J) + D(K) * F(I, J, K)
```
- ```
3. DO I = 1, N
 DO K = 1, N
 A(I) = A(I) + X(I,K)
 ENDDO
 DO J = 1, M
 DO K = 1, N
 B(J,K) = B(J,K) + A(I)
 ENDDO
 C(J,I) = B(J,N)/A(I)
 ENDDO
ENDDO
```