Scaling alignment of large ontologies

Suzette K. Stoutenburg* and Jugal Kalita
The College of Engineering and Applied Science,
University of Colorado,
Colorado Springs, CO 80918, USA
E-mail: suzette@coloradostoutenburg.com
E-mail: kalita@eas.uccs.edu
*Corresponding author

Kaily Ewing and Lisa M. Hines
The College of Letters, Arts and Sciences,
University of Colorado,
Colorado Springs, CO 80918, USA
E-mail: kewing@uccs.edu
E-mail: lhines@uccs.edu

Abstract: In recent years, the number of shared biomedical ontologies has increased dramatically, resulting in a need for integration of these knowledge sources. Automated solutions to aligning ontologies address this growing need. However, only very recently, solutions for scalability of ontology alignment have begun to emerge. This research investigates scalability in alignment of large-scale ontologies. We present an alignment algorithm that bounds processing by selecting optimal subtrees to align and show that this improves efficiency without significant reduction in precision. We apply the algorithm in conjunction with our approach that includes modelling ontology alignment in a Support Vector Machine.

Keywords: knowledge acquisition; knowledge management; machine learning; ontology; ontology alignment; semantic technology; SVMs; support vector machines.


Biographical notes: Suzette K. Stoutenburg received her PhD in Computer Science from the University of Colorado at Colorado Springs in 2009. She is a Principal Engineer at the MITRE Corporation. Her dissertation focused on developing methods to integrate knowledge sources using non equivalence relations in the biomedical domain as well as scaling the performance of large ontology alignments.

Jugal Kalita is a Professor in the Department of Computer Science at the University of Colorado at Colorado Springs. He received his BTech in Computer Science and Engineering from the Indian Institute of Technology, Kharagpur; an MSc in Computational Science from the University of Saskatchewan; and an MS and a PhD, both in Computer and Information...
Science from the University of Pennsylvania. His research interests include bioinformatics, machine learning, natural language processing and information retrieval.

Kaily Ewing is a Graduate student at the University of Colorado and will receive her Master’s Degree in Biology in the spring of 2010. Her research interests include developmental biology, genetics, and epidemiology.

Lisa M. Hines received her ScD in Epidemiology at Harvard School of Public Health, Boston, MA. She is an Assistant Professor in the Department of Biology at the University of Colorado at Colorado Springs. Her research interests include epidemiology, genetics, proteomics and cancer biology.

1 Introduction

The number of ontologies available on the web has increased significantly in recent years, particularly in the Biomedical domain; for example, the Open Biomedical Ontologies (OBO) (Smith et al., 2004) and the Gene Ontology (GO) (Ashburner et al., 2000). However, as different parties generate ontologies independently, the level of heterogeneity across platforms increases (Euzenat and Shvaiko, 2007). And, despite use of a standard language for ontology representation, such as OWL, there are still vast differences in ontology design. Therefore, there is a growing need to integrate ontologies using automated methods.

To reduce the impediments to integrating data sources using ontologies, researchers are seeking to apply ontology alignment techniques to automatically discover relationships across ontological components. Ontology alignment (also referred to as matching (Euzenat and Shvaiko, 2007; Rahm and Bernstein, 2001), mapping (Noy, 2004), and merging (Noy and Musen, 2003)), is the process of discovering relationships between entities across two or more ontologies based upon a variety of techniques that use entity labels, structure, semantics, and external resources to determine the relationships. We will use the term ontology alignment in this work. Ontology alignment is viewed as a potential solution to a broad set of challenges, including data integration, agent negotiation, and web service composition (Ehrig, 2007) as well as peer-to-peer information sharing and advanced navigation and query answering on the web (Euzenat and Shvaiko, 2007).

The original goal of this research was to apply a SVM approach to align large-scale biomedical ontologies using non equivalence relations. Details of this approach can be found in Stoutenburg (2009). At the onset of large-scale testing, however, we encountered significant challenges in opening large-scale ontologies for processing. We found similar challenges even when using open source tools that are widely used in the semantic community, such as the Protege tool for editing and managing ontologies. In addition, when feature extraction for the SVM was applied in the alignment process, the application ran initially for up to three days when processing fairly small numbers of ontology pairs. Therefore, it became apparent that investigating scalability would be an essential part of this research. Our work in this area is the focus of this paper.
2 Related work

In 2009, scalability of ontology alignment remains a key challenge and approaches to address the challenge are only starting to emerge. In the Ontology Alignment Evaluation Initiative (OAEI)\(^1\) in 2007 and 2008, participants were encouraged to align large data sets, including the Anatomy, Food and Library ontologies (Euzenat et al., 2007; Caracciolo et al., 2008). However, only four of seventeen tools accomplished alignment tasks with the largest ontologies in OAEI 2007 and only three in OAEI 2008. Paulheim found that the very large biomedical ontologies, such as GO and NCI Thesaurus\(^2\) cannot be processed by top performing ontology alignment tools (Paulheim, 2008).

To date, research into developing scalable infrastructures for processing and reasoning over ontologies has been in two main areas: first, developing a representation approach that combines semantic richness (i.e., expressiveness) with scalable performance; and second, harnessing the power and scalability of database systems to represent ontologies (Hepp et al., 2008). Solutions to scaling ontology alignment are only starting to emerge. In fact, scalability continues to be one of the grand challenges of ontology construction and use (Hepp et al., 2008) and scaling ontology alignment in particular remains a research area (Giunchiglia et al., 2009).

Some early attempts at scaling ontology alignment include elimination of candidates prior to alignment. Typically, light-weight string-based matching has been applied for candidate elimination in large-scale ontology alignment; for example (Zhang and Bodenreider, 2007; Kirsten et al., 2007). The problem with these approaches is that they are comparing lexical instead of semantic qualities of ontological classes. Thus, this approach risks reduced accuracy, specifically, reduced recall. Some of the more successful approaches that use string-based matching to eliminate candidates perform alignment using domain-specific knowledge sources (Zhang and Bodenreider, 2007; Kirsten et al., 2007). Use of domain-specific knowledge sources, however, precludes these solutions from performing successful alignment in other domains. Other work has adapted match algorithms to reduce the use of memory. Mork showed how large biomedical ontologies, the Foundational Model of Anatomy (FMA) and Galen,\(^3\) could be aligned by considering only direct subclasses and superclasses of each class to align. This work was successful in aligning large biomedical ontologies, but it is important to note that the ontologies were not expressed in OWL, instead a frame-based system was used (Mork and Bernstein, 2004).

Very few alignment approaches have addressed the challenges of large scale ontology alignment. In OAEI 2007, only four of seventeen approaches aligned the largest ontologies, including the Anatomy, Food and Library tracks (Euzenat et al., 2007). One approach, DSSIM, applied manual partitioning in order to process the large ontologies (Nagy et al., 2007). Others, including RIMOM (Tang et al., 2006) and PRIOR+ (Mao and Peng, 2007) applied light-weight string-matching techniques as alternatives to full-scale alignment. An approach by Wang and Xu was presented at OAEI 2007 called Lily, but Lily did not align the largest ontologies until OAEI 2008. Wang and Xu refer to a scalability approach “generic ontology matching method based on semantic subgraphs”, but this work has not yet been published (Wang and Xu, 2008). At the Ontology Matching workshop in 2008, Paulheim proposed two
approaches to enhance the scalability of ontology alignment: overlapping partitions and optimised thresholding (Paulheim, 2008). These are discussed in further detail in Section 3.

Partitioning ontologies as an approach to improving scalability is risky, since most ontology alignment approaches rely on ontological structure to some degree. Performed naively, partitioning could lead to significant degradation in alignment accuracy. One approach to avoiding this issue involves the creation of overlapping partitions. In this approach, the direct neighbours of each concept are included in the partition, thus creating overlapping partitions. This approach has shown significant improvement in alignment accuracy though there is significant cost in time complexity (Paulheim, 2008).

A divide-and-conquer strategy for alignment is described by Hu in late 2008 (Hu et al., 2008). In this approach, ontologies are partitioned into blocks by measuring structural proximity, with each block being labelled with RDF sentences (Zhang et al., 2007). Each block is mapped using entities matched beforehand and alignments are determined across blocks (Hu et al., 2008). Hu reports that this approach reduced execution time of alignment, down to 12 min for the OAEI Anatomy track. By comparison, in OAEI 2008, DSSIM, RIMOM and PRIOR+ report execution times of 4 h, 75 min and 23 min, respectively. However, the execution time for partitioning is not reported. Based on our results (Stoutenburg, 2009), we believe this is because the partitioning likely took days to run even on moderately sized ontologies. Furthermore, Hu’s structural proximity matrix does not consider the qualitative properties of the relations between ontological nodes. Each link in the graph is treated as if were the same relation. Thus, if the relation between ontological concepts is a non equivalence relation, then the structural proximity matrix approach breaks down in alignment.

Stuckenschmidt and Klein propose an algorithm for partitioning ontologies in which the degree of dependency between concepts is measured, but the semantics of the partitions are not maintained (Cuenca-Grau et al., 2007). Algorithms are proposed in Noy and Musen (2003) and Seidenberg and Rector (2006) to partition ontologies by traversing relationships between concepts and produce stand-alone fragments. However, as pointed out in Cuenca-Grau et al. (2007), these approaches do not characterise the logical properties of the extracted fragments. The notion of ontology modules and methods for extracting them are formally defined in Cuenca-Grau et al. (2007). These efforts partition ontologies based on the semantics. However, despite the high accuracy of the results in Cuenca-Grau et al. (2007) for example, these partitioning methods often result in modules (or partitions) that are still quite large, on the order of thousands of classes (Hu et al., 2008).

3 Definitions

3.1 Ontology

Typically, definitions of ontology are designed to meet the goals of the researcher but there are some core components that comprise any definition. At a minimum, an ontology can be defined to consist of a nonempty set of classes, a nonempty set of relations, a hierarchy among classes, a hierarchy among properties, and a set of functions that map classes via properties, the latter being an expression of class relationships. Ehrig defines
this set of features as Core Ontology (Ehrig, 2007). Some definitions of ontology include instances (Euzenat and Shvaiko, 2007) while others define instances and the instantiation function to be part of a Knowledge Base (Ehrig, 2007). Interestingly, Euzenat explicitly defines a subset of relations that exist in an ontology, such as subclass (he calls it specialisation), disjointness (exclusion), instantiation and assignment (Euzenat and Shvaiko, 2007). Euzenat also defines data types to be part of an ontology while Ehrig defines data types to be a special case of class. Also, Ehrig states that an ontology must consist of a lexicon that defines the names of classes and relations and a lexical reference for those names. We prefer Ehrig’s approach to defining ontology since it provides a modular definition of the components of an ontology in such a way that operations and algorithms can be more precisely defined. However, we use some elements of both approaches in the definition below.

**Definition 1** (Ontology): An ontology is a 6-tuple $\mathcal{O} = \langle C, R, \leq_C, \leq_R, \sigma, A \rangle$, such that:

- $C$ is a nonempty set of classes: $\{C_1, C_2, ..., C_n\}$
- $R$ is a nonempty set of relations: $\{R_1, R_2, ..., R_n\}$
- $C, R$ are disjoint
- $\leq_C$ is a class hierarchy, a partial order on $C$
- $\leq_R$ is a relationship hierarchy, a partial order on $R$
- $\sigma: R \rightarrow C \times C$, representing relationships between classes
- $A$ is a set of class axioms, possibly empty: $\{A_1, A_2, ..., A_n\}$.

Note that in this work, we do not operate over instances. Therefore, we leave instances out of the definition of ontology.

Similar to Ehrig’s definition, we denote that if $c_1 \leq_C c_2$, where $c_1, c_2 \in C$, then $c_1$ is a subclass of $c_2$ and $c_2$ is a superclass of $c_1$. If $c_1 \leq_C c_2$, and $\exists$ $c_3 \in C$ such that $c_1 \leq_C c_3 \leq_C c_2$, then $c_1$ is a direct subclass of $c_2$ and $c_2$ is a direct superclass of $c_1$. We also borrow, in part from Ehrig, the concept of a set of entities and we say that an entity $e \in \mathcal{E}$ in ontology $\mathcal{O}$ is a class or relation, such that $e_\mathcal{O} \in C \cup R$. We treat data types as a set $D \subseteq C$, i.e., a special set of classes, as in Euzenat and Shvaiko (2007).

### 3.2 Ontology alignment

To formally define ontology alignment, we first define correspondence, inspired by Ehrig (2007). This definition uses the same sets $C, R$, and $E$ defined above.

**Definition 2** (Correspondence): Consider two ontologies $\mathcal{O}_i$, $\mathcal{O}_j$. Let $C_i$ and $R_i$ represent classes and relations in $\mathcal{O}_i$, respectively. Let $C_j$ and $R_j$ represent classes in $\mathcal{O}_j$, respectively. A correspondence CORR is a 4-tuple $\text{CORR} = \langle e_i, e_j, \phi, p \rangle$, where:

- $e_i \in \mathcal{O}_i$, $e_j \in \mathcal{O}_j$
- if $e_i \in C_i$, then $e_j \in C_j$, or if $e_i \in R_i$, then $e_j \in R_j$
- $\phi$ represents a nonempty set of relationships
• $\leq_c$ is a class hierarchy, a partial order on $C$

• $p \in \mathbb{R}$ such that $p \in [0, 1]$, denoting a confidence on the relationship $\phi$.

We define $\phi$ as the set of relationships that will be acquired using ontology alignment techniques. These relations may not exist in the ontologies. For example, most ontology alignment techniques seek to acquire equivalence across ontological entities. In this work, we seek to acquire hyponymy. However, our work is distinguished from previous work in ontology alignment because we also seek to discover what we call generic relation $r$; that is, we seek to acquire relations between ontological entities $e_i, e_j$ that exist in at least one of the ontologies. This is shown in and explained further in Section 4.

Given this definition of correspondence, we can now define an ontology alignment, which is very similar to Ehrig (2007).

**Definition 3** (Ontology alignment): An ontology alignment is a set of correspondences.

### 3.3 Relations used to align ontologies

One of the primary goals of this research is to acquire relationships between ontological entities beyond similarity and equivalence. As discussed in Section 2, we define the set of relationships $\phi$ as a special set of relationships between entities that our algorithms are designed to discover. These relationships include the following.

- **Hyponymy**, a relation that denotes a subcategory of a more general class.
- **Hypernymy**, a relation that denotes a generalisation of a more specific class.
- Correspondences such that $\phi \in R_i \cup R_j$; that is, we will discover properties across ontological entities that are defined in the original ontologies, as depicted in Figure 1. We will define these set of relations to be in the set General Relation $r$.

**Figure 1** Example of mapping classes cross-ontology using relationships within the original ontologies (see online version for colours)
4 Domain for alignment

In this work, we performed ontology alignment in the Biomedical domain. We chose to align components of the GO (Ashburner et al., 2000) with the Mammalian Phenotype (MP) ontology (Smith et al., 2004), part of the OBO. The GO provides a controlled vocabulary to describe gene and gene product attributes in any organism (Ashburner et al., 2000). It consists of three major categories of descriptors: biological processes, molecular function and cellular component. The MP ontology supports annotation of mammalian phenotypes in the context of mutations, quantitative trait loci and strains that are used as models of human biology and disease (Smith et al., 2004). The MP ontology is primarily based on experimental studies conducted using mouse as the model organism. We chose to align these two ontologies because:

- they are well-developed and frequently updated
- they are widely used by the biomedical research community
- they have great potential for application in the area of translational research.

For example, discoveries in experiments conducted with mice could then be linked to various gene products that may share similar GO attributes, which may ultimately contribute to hypothesis generation with regard to human disease development. Details on the ontologies used in this evaluation are provided in Table 1.

Table 1  Biomedical ontologies used in performance evaluation

<table>
<thead>
<tr>
<th>†</th>
<th>Ontology</th>
<th>OWL classes</th>
<th>OWL object properties</th>
</tr>
</thead>
<tbody>
<tr>
<td>go</td>
<td>Gene Ontology <a href="http://www.geneontology.org/">http://www.geneontology.org/</a></td>
<td>26763</td>
<td>4</td>
</tr>
<tr>
<td>mp</td>
<td>Mammalian Phenotype ontology</td>
<td>29205</td>
<td>1</td>
</tr>
</tbody>
</table>

The column denoted with † is used to indicate the short name of the ontology, for reference throughout this document.

5 Ontology alignment approach

We modelled ontology alignment in a SVM. Consider a set of ontologies we collect from the web: \( O = o_1, o_2, \ldots, o_e \). We operate over one ontology pair at a time. Let an ontology pair be \((o_i, o_j)\). Let the set of \( k \) classes in ontology \( o_i \) be denoted by \( c_{i1}, c_{i2}, \ldots, c_{ik} \). Let the set of \( l \) classes in ontology \( o_j \) be denoted by \( c_{j1}, c_{j2}, \ldots, c_{jl} \). Let \( R \) be the set of non equivalence relations to acquire cross-ontology; that is, \( R = \{ \text{subclass, superclass, inferred relations} \} \). Ontology alignment is the process of evaluating each class pair \((c_{ik}, c_{jl})\) to see if a relationship in \( R \) exists between them. We model this process in an SVM by letting each object in the SVM represent a class pair. We model a set of features that exist between each class pair in order to evaluate whether \( R \) exists between the pair.
There are five main types of features used in this work to identify correspondences: pattern-based (which use semantics, structure and external data sources), string-based, linguistic-based, bag-of-word-based and extrinsic-based (which include syntactic and semantic knowledge). We selected features that are domain-independent so that the models can be used broadly. There were over 50 features defined over all relations types in the SVM, with over 20 used per relationship type. There was a heavy reliance on pattern- and linguistic-based approaches as well as use of the OpenCyc upper ontology and WordNet. We used string-based features that include simple comparisons such as, detection that class names in a pair end with the same $n$ words. Another feature detects if words end in the same substring. We also use the string metric by Stoilos et al. (2005). This approach scores based on the largest common substring between strings and has been shown to enhance performance in ontology alignment using equivalence. Some of the linguistic-based features include detection of meaningful prefixes in strings, such as sub-, super- and others that might suggest a subclass relationship, for example. We also used bag-of-word processing to extract features of class pairs. This was particularly useful in ontologies in which class names consisted of multiple words, typical for biomedical ontologies. For example, we scored the number of synonyms, hyponyms and hypernyms in each class pair. Interestingly, we used an additional string-based technique to obtain inferred relationships cross-ontology. We performed a string distance metric that operated over the relationship name from the original ontology and each of the class names in different combination. This was designed to identify relationships across the biomedical ontologies, such as \textit{PositiveRegulationOfPlateletActivation positivelyRegulates PlateletActivation}. Finally, extrinsic data sources were used in our feature extractors. We detect syntactic and semantic relationships between the class names using online knowledge sources, in particular, WordNet and OpenCyc. WordNet and OpenCyc are consulted to identify direct relationships between class pairs, such as synonymy, hyponymy and hypernymy. The sources are used to identify direct relationships between classes in a pair but are also used in the patterns described earlier in this section. The complete set of evidence primitives used to align provided in Stoutenburg (2009).

The architecture used in this work for ontology alignment is shown in Figure 2. The architecture consists of a Feature Extractor and SVM. The Feature Extractor identifies the features that exist between each class pair using the feature types described in Stoutenburg (2009). The Feature Extractor applies multiple techniques, including string-, linguistic-, structure-, semantic- and pattern-based approaches to derive features. In addition, it makes use of OWL semantics and consults external knowledge sources including OpenCyc and WordNet. The Feature Extractor represents each class pair as a vector of features identified. The SVM utilises training data to optimise parameters and to construct a model. The SVM model is used to predict class membership between each class pair; it predicts whether a particular relationship exists between each class pair based on the features extracted. Of course, a unique Feature Extractor and SVM model were developed for each relationship to be acquired. The alignment result is expressed as an XML 4-tuple, including each class from the class pair, the relationship, and a relationship indicator indicating whether the relationship exists between the pair. In this work, we predicted discrete values, so the relationship indicator is $\in [0, 1]$. 

\[ \text{Scaling alignment of large ontologies} \]
6 Metrics for large-scale ontology alignment

Determining precision and recall in large-scale ontology alignment is difficult. Ideally, we would have access to a complete reference alignment with all ‘true’ results; but to build such a set a data for large-scale alignments is manual, difficult and time-consuming, requiring large groups of domain experts. This is particularly true in alignments with non equivalence relations. Data sets with known results for alignment with subclass, superclass and inferred relations simply do not yet exist. Therefore, it is necessary to use metrics that estimate precision and recall. We decided to use a set of metrics proposed by Kirsten et al. (2007) which applies rough approximations for precision and recall using relative quality measures. Kirsten identifies two primary accuracy approximation metrics: match coverage, designed to approximate recall, and match ratio, designed to approximate precision. Match coverage essentially measures how many classes are identified in the alignment. Let $c_{o_1}$ be the set of all classes in ontology $o_1$ and let $c_{1\text{-match}}$ be the set of concepts in $o_1$ that appear in any alignment pair. Let $c_{o_2}$ be the set of all classes in ontology $o_2$ and let $c_{2\text{-match}}$ be the set of concepts in $o_2$ that appear in any alignment pair. Then,

$$\text{MatchCoverage}_{o_1} = \frac{|c_{1\text{-match}}|}{|c_{o_1}|}$$

$$\text{MatchCoverage}_{o_2} = \frac{|c_{2\text{-match}}|}{|c_{o_2}|}.$$ 

According to Kirsten, high match coverage indicates that a significant number of concepts were matched. For example, 90% match coverage would indicate that 90% of the classes are matched, which would suggest high recall. Therefore, Kirsten recommends attaining match coverages that are high, above 60%. This metric assumes that it is expected that a large number of concepts should match across ontologies.
This may not always be the case, so low match coverage measures may not necessarily be an indicator of poor recall.

To estimate precision, match ratio measures the ratio between the number of correspondences and the number of matched concepts. The idea is that precision of a matched result is better if a single concept is matched to fewer concepts (preferably similar concepts) and not loosely matched (Kirsten et al., 2007). To define match ratio, let $corr_{o_1,o_2}$ be the correspondences found in the alignment process. Then,

$$
MatchRatio_{o_1} = \frac{|corr_{o_1,o_2}|}{|o_1\text{-match}|}
$$

$$
MatchRatio_{o_2} = \frac{|corr_{o_1,o_2}|}{|o_2\text{-match}|}
$$

The combined match ratio is defined similar to $f$-score, as follows:

$$
CombinedMatchRatio = \frac{2 \times |corr_{o_1,o_2}|}{|o_1\text{-match}| + |o_2\text{-match}|}
$$

Match ratios that are too high indicate concepts mapped to many other concepts, a suggestion of low precision. Match ratios close to 1.0 indicate the highest precision. Kirsten states that match ratios between 2–9 indicate reasonable levels of precision.

We use these set of metrics to estimate precision and recall in our large-scale alignment results. We also perform random spot checks of the resultant alignments to strengthen confidence in the results.

7 Optimising ontology alignment with a Branch and Bound approach

To improve scalability of alignment, we developed an algorithm based on a Branch and Bound approach. This algorithm considers each concept in ontology $o_i$ and semantically compares it with concepts in ontology $o_j$ seeking to eliminate subtrees in ontology $o_j$ that are not likely to align. The algorithm moves depth first through the graph of $o_j$; if a concept in $o_j$ is not semantically close to the concept under consideration in $o_i$, it is pruned from further consideration along with all of its children. Once the pairs of concepts to align are selected, alignment begins. This algorithm is designed to reduce the time complexity such that $O(n^2)$ is a maximum; the actual complexity is typically much less, depending on the number of semantically close concepts cross-ontology. This approach is detailed in Figure 3.

The most important component of this algorithm is the method used to evaluate whether two concepts are ‘semantically close’. Semantic closeness is determined by the relationship that we seek to acquire in the alignment. For example, if we seek to align using subclass relationships, then ‘semantic closeness’ might be defined to be the existence of hyponymy relations among words in class names cross-ontology. If we seek to align using superclass relationships, then we might define ‘semantic closeness’ to be the existence of hypernymy relations among words in class names cross-ontology. Our goal was to select a feature set that would prune unlikely candidates, resulting in a computationally inexpensive yet still highly accurate approach. Depending on the feature selected, we could expect to encounter varying execution times as well as varying
accuracy results. As a starting point to align with subclass, we selected a feature that measures how many hyponyms occur between class names cross-ontology.

**Figure 3** The algorithm for branchAndBoundAlign($o_i, o_j$)

```plaintext
FOR each root concept $c_j \in o_j$
   push $c_j$ onto stack;
ENDFOR
FOR each concept $c_i \in o_i$
   WHILE (not done)
      IF (stack is empty)
         done = true;
      ELSE
         $c_i$ = pop stack;
         IF (semanticallyClose($c_i, c_j$))
            pairsToCompare.add($c_i, c_j$)
            push direct subclasses of $c_j$ onto stack;
      ENDIF
   ENDIF
ENDWHILE
ENDFOR
Align(pairsToCompare)
```

The evaluation was performed by aligning the Mammalian Phenotype (MP) Ontology and the Biological Process subset of the Gene Ontology (gobp) using subclass relations, with bag of words hyponymy used as the semantic distance check. As shown in Figure 4, the algorithm results in a dramatic reduction in execution time over the original alignment algorithm. The Branch and Bound algorithm aligns in an average of approximately 38 h as compared to an average of 96 h with the original alignment algorithm. On average, we found that time complexity was cut by approximately 1/3.

**Figure 4** Branch & Bound alignment performance comparison for up to 1000 pairs (including time to select pairs to align) (see online version for colours)

To complete our assessment of the value of the Branch and Bound algorithm, we evaluated whether the algorithm results in a reduction in accuracy. To do that, we compared the performance of the Branch and Bound algorithm with the performance of the original method when aligning the mp and gobp ontologies. To measure accuracy, we used the approximation metrics described in Section 6. The evaluation was performed with the SVM models built for the Biomedical domain in an earlier part of this research.
We averaged the performance over 3 SVM models. The semantic distance test was performed using the features that measure how many hyponyms appear between words in each class name. A comparison of the average match coverage metrics, which estimate recall, are shown in Figure 5. These results show that estimated recall is significantly lower, particularly for the second ontology. This is not entirely unexpected, given the nature of the algorithm; i.e., we might expect that less classes in ontology 2 are matched, since they are being pruned in the process. Recall from Section 6 that Kirsten recommends match coverage to be above 60%; however, we believe that in this case, low match coverage may not necessarily be an indicator of poor recall. However, we will still seek to improve the match coverage of the Branch and Bound algorithm. Match ratios, on the other hand, are satisfactory since they fall well within the range recommended by Kirsten, as shown in Figure 6. This suggests that precision is not negatively impacted by the Branch and Bound approach. Recall from Section 6 that we seek match ratios in the range of 2–9, with 1 being considered a perfect score. Therefore, these results are quite encouraging. Given the nature of the Branch and Bound algorithm, we would expect that precision should remain as high as the original approach, since the alignment process remains constant. These estimated metrics were validated with random spot checks of the alignments by biomedical researchers. Their results were favourable with roughly 80% of the alignments being correct.

Figure 5  Comparison of large-scale alignment accuracy of Branch & Bound and Original Algorithm using match coverage (an estimate of recall) (see online version for colours)

Figure 6  Comparison of large-scale alignment accuracy of Branch & Bound and Original Algorithm using match ratio (an estimate of precision) (see online version for colours)
The key to improving recall of the algorithm is to select the optimal feature for use in pruning, the feature that best determines ‘semantic closeness’. This set of features should result in higher recall but not significantly increase processing time. Therefore we performed experiments to identify optimal semantic distance features for use in the for subclass alignment. We compared the following features to determine if they would improve recall.

- hyponyms between words in class names cross-ontology
- hypernyms between words in class names cross-ontology
- synonyms between words in class names cross-ontology
- hyponyms and hypernyms between words in class names cross-ontology.

The results are shown in Figure 7. Again, these experiments involved aligning the mp and gobp ontologies. We found that using the feature to detect hyponyms between class terms worked the best of all the single features. However, this was the feature originally used, therefore recall was not improved. Combining hypernyms and hyponyms worked best overall, delivering a slight improvement in recall. However, even with the combination of features, recall remains quite low. The use of match coverage as an estimation of recall may be flawed however, since the measure assumes all classes must be matched. With this limitation in mind, we believe that utilising domain resources is the likely solution to optimising recall for the Branch and Bound algorithm. The disadvantage, of course, is that the solution will not work in all domains.

Figure 7  Comparison of match coverage performance of features to detect semantic closeness (see online version for colours)

In the case of the Stoilos metric, the algorithm execution time was higher, more than 50% higher, therefore, we abandoned that approach for semantic closeness. In addition, we did not expect that a string metric would yield good results for semantic distance. In all other cases, execution time was not significant increased over the results discussed earlier in this section; in all cases, execution time remained within 5% of the original optimisation.
8 Experimental results: alignment of large scale biomedical ontologies

In this section, we present the results for aligning large-scale ontologies from the OBO collection using subclass relations. We aligned eight pairs of ontologies using the SVM models developed in earlier work. Recall that we use match coverage and match ratios to estimate recall and precision, respectively. A comparison of match coverage can be seen in Figure 8. In most cases, the alignment performs well. In particular, the NCI Thesaurus (nci) and Mouse Anatomy (ma) alignments result in strong match coverage, as do alignments of the Mammalian Phenotype (mp) and Mouse Anatomy (ma). This is especially encouraging since the SVM models were trained on mp, gobp examples, primarily. Match coverage performance on mp, gobp is also very good.

Match coverage for pairs mp, gomf and mp, gocc is not as strong. An analysis of the results revealed that many features were extracted for class pairs. For example, in the mp, gomf pair, features were extracted in well over 8000 class pairs. However, in most cases, only single features were identified. The SVM was trained with positive examples that typically possessed multiple features. Therefore, this suggests that the SVM should be trained with a more diverse set of data. In addition, further analysis is needed to identify features that will result in better match coverage for a broader set of ontologies in the Biomedical domain. However, it should also be noted that Kirsten’s metric is a rough estimate, since it assumes that all classes must have a match. Clearly, that is not a reasonable expectation in a complex domain such as Biomedical.

Figure 8  Match coverage for alignment of large-scale biomedical ontologies (estimate of Recall) (see online version for colours)

Match ratio comparisons of large-scale alignment using subclass relations are shown in Figure 9. Again, in most cases, estimated precision looks very good. This is especially promising given that the SVM models were trained on mp, gobp examples, primarily. The estimated precision in the pair mp, gomf is troublesome; the results show that an inordinate number of matches occur in mp, an unexpected result. An analysis of the results showed that in fact, too many single classes were being matched to multiple classes, an indicator of low precision. Random spot checks confirmed low precision. This suggests that additional features should be identified and incorporated into the SVM to improve precision in a broader set of class pairs. However, overall, estimated precision is within the acceptable range (2–9), per Kirsten. In fact, Kirsten’s precision results were in the range of 8–46 in the Biomedical domain (Kirsten et al., 2007). This suggests that our approach is highly precise.
Note that we supplemented these results with spot checks of the alignments by biomedical researchers. Data to spot check was selected randomly. The results were favorable in general, with roughly 80% of the alignments being successful. This is an encouraging result and strengthens our confidence in the use of the estimation metrics.

**Figure 9** Match ratios for alignment of large-scale biomedical ontologies (estimate of Precision) (see online version for colours)

9 Conclusions

Solutions to scaling ontology alignment are only starting to emerge. In fact, scalability continues to be one of the grand challenges of ontology construction and use (Hepp et al., 2008) and scaling ontology alignment in particular remains a research area (Giunchiglia et al., 2009). We analysed some approaches in this paper; in particular, we looked at Hu’s approach to ontology partitioning using a divide and conquer approach (Hu et al., 2008). Hu’s algorithm does not consider the qualitative nature of links between classes and the execution time of partitioning is not reported. While pushing the complexity of alignment to an a priori process is a good approach (as it takes steps toward near real-time alignment), we found that Hu’s approach is too expensive computationally.

We briefly described our approach to ontology alignment using non equivalence relations. To scale ontology alignment, we presented an algorithm that is based on a Branch and Bound approach. In this novel approach, the algorithm considers each concept in the first ontology and compares it, depth first, to concepts in the second ontology. If the concept pairs are not ‘semantically close’, then the concept in ontology 2 is pruned from further consideration as are its children. This approach caps the maximum time complexity at $O(n^2)$, and on average, we found that time complexity was cut by 1/3.

Since reference alignments for large-scale ontology alignments are not available and not feasible to create, we used emerging metrics from Kirsten et al. (2007) to approximate precision and recall. We found that the Branch and Bound approach did not significantly reduce precision but it did reduce recall. We worked to identify functions to optimise the tradeoff between execution time and recall. We found that hyponymy relations between class names worked best as a single feature to identify semantic closeness. Identification of hyponymy relations in conjunction with hypernymy relations
cross-ontology worked best to improve recall, without significant increase in execution time. Precision remained at fairly high levels in these experiments.

Finally, we present large-scale alignments of biomedical ontologies using subclass relations. In most cases, the algorithms performed well, according to estimated metrics and random spot checks. Alignment performed well even on ontologies that were not used in training the SVMs, such as the nci, ma and ma, nci pairs. In a few cases, we did find that performance was not satisfactory, as in the case of the mp, gomf and mp, goce pairs. Analysis of the results showed that performance could be improved in two ways:

- by adding new features to the SVM
- by training the SVM with a broader set of training examples.

In general, however, our results suggest that our approach is feasible for use in real world applications, in terms of time complexity and accuracy.

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Notes

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