Intermediate Representation

Abstract syntax tree, controlflow graph, three-address code

Intermediate Code Generation

- Intermediate language between source and target
- Multiple machines can be targeted
 - Attaching a different backend for each machine
 - Intel, AMD, IBM machines can all share the same parser for C/C++
- Multiple source languages can be supported
 - Attaching a different frontend (parser) for each language
 - Eg. C and C++ can share the same backend
- Allow independent code optimizations
 - Multiple levels of intermediate representation
 - Supporting the needs of different analyses and optimizations

IR In Compilers

- Internal representation of input program by compilers
 - Source code of the input program
 - Results of program analysis
 - Control-flow graphs, data-flow graphs, dependence graphs
 - Symbol tables
 - Book-keeping information for translation (eg., types and addresses of variables and subroutines)
- Selecting IR --- depends on the goal of compilation
 - Source-to-source translation: close to source language
 Parse trees and abstract syntax trees
 - Translating to machine code: close to machine code
 Linear three-address code
- External format of IR
 - Support independent passes over IR

Abstraction Level in IR

- Source-level IR
 - High-level constructs are readily available for optimization
 Array access, loops, classes, methods, functions
- Machine-level IR
 - Expose low-level instructions for optimization
 - Array address calculation, goto branches



Source-level tree

ILOC code

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Parse Tree And AST

- Graphically represent grammatical structure of input program
 - Parse tree: tree representation of syntax derivations
 - AST: condensed form of parse tree
 - Operators and keywords do not appear as leaves
 - Chains of single productions are collapsed



Implementing AST in C

Grammar:

:	E ::= E + T E - T 1	Γ
	T ::= (E) id num	

- Define different kinds of AST nodes
 - typedef enum {PLUS, MINUS, ID, NUM} ASTNodeTag;
- Define AST node types
 - typedef struct ASTnode {
 AstNodeTag kind;
 union { symbol table ontry
 - union { symbol_table_entry* id_entry;
 - int num_value;

```
struct ASTnode* opds[2];
```

} description;

};

- Define AST node construction routines
 - ASTnode* mkleaf_id(symbol_table_entry* e);
 - ASTnode* mkleaf_num(int n);
 - ASTnode* mknode_plus(struct ASTnode* opd1, struct ASTNode* opd2);
 - ASTnode* mknode_minus(struct ASTnode* opd1, struct ASTNode* opd2);

Implementing AST in Java

Grammar:

E ::= E + T | E – T | T T ::= (E) | id | num

Define AST node

abstract class ASTexpression {

public System.String toString();

}

class ASTidentifier extends ASTexpression { private symbol_table_entry id_entry; ... }
class ASTvalue extends ASTexpression { private int num_value; ... }
class ASTplus extends ASTexpression { private ASTnode opds[2]; ... }

Class ASTminus extends ASTexpression { private ASTnode opds[2]; ... }

- Define AST node construction routines
 - ASTexpression mkleaf_id(symbol_table_entry e)
 - { return new ASTidentifier(e); }
 - ASTexpression mkleaf_num(int n)
 - { return new ASTvalue(n); }
 - ASTexpression mknode_plus(ASTnode opd1, struct ASTNode opd2) { return new ASTplus(opd1, opd2);
 - ASTexpression mknode_minus(ASTnode opd1, struct ASTNode opd2) { return new ASTminus(opd1, opd2);

Constructing AST

Use syntax-directed definitions

- Associate each non-terminal with an AST
 A pointer to an AST node: E.nptr T.nptr
- Evaluate synthesized attribute bottom-up
 - From children ASTs, compute AST of the parent

E ::= E1 + T	<pre>{ E.nptr=mknode_plus(E1.nptr,T.nptr); }</pre>
E ::= E1 – T	<pre>{ E.nptr=mknode_minus(E1.nptr,T.nptr); }</pre>
E ::= T	{ E.nptr=T.nptr; }
T ::= (E)	<pre>{T.nptr=E.nptr; }</pre>
T ::= id	<pre>{ T.nptr=mkleaf_id(id.entry); }</pre>
T ::= num	{ T.nptr=mkleaf_num(num.val); }

Exercise: what is the AST for 5 + (15-b)? What if top-down parsing is used (need to eliminate left-recursion)?

Example: AST for 5+(15-b)

Bottom-up parsing: evaluate attribute at each reduction

Parse tree for 5+(15-b)



- 1. reduce 5 to T1 using T::=num: T1.nptr = leaf(5)
- 2. reduce T1 to E1 using E::=T: E1.nptr = T1.nptr = leaf(5)
- 3. reduce 15 to T2 using T::=num: T2.nptr=leaf(15)
- 4. reduce T2 to E2 using E::=T: E2.nptr=T2.nptr = leaf(15)
- 5. reduce b to T3 using T::=num: T3.nptr=leaf(b)
- 6. reduce E2-T3 to E3 using E::=E-T: E3.nptr=node(`-',leaf(15),leaf(b))
- 7. reduce (E3) to T4 using T::=(E): T4.nptr=node(`-',leaf(15),leaf(b))
- 8. reduce E1+T4 to E5 using E::=E+T:

```
E5.nptr=node(`+',leaf(5),
```

node(`-',leaf(15),leaf(b)))

Symbol tables

Symbol tables

- Record information about names defined in programs
 - Types of variables and functions
 - Additional properties (eg., static, global, scope)
- Contain information about context of program fragment
 Can use different symbol tables for different purposes

Naming conflicts

- The same name may represent different things in different places
 - Use separate symbol tables for names in different scopes
 - Multiple layers of symbol tables for nested scopes
- Implementation of symbol tables
 - Map names to additional information (types, values, etc.)
 - Efficient implementation: using hash tables

Implementing symbol tables

Interface

- Lookup(name)
 - Returns the record for name if one exists in the table; otherwise, indicates that name is not found
- Insert(name, record)
 - Stores the information in record in the table for name.
- Symbol tables in nested scopes
 - StartNewScope()
 - Increment the current scope level and creates a new symbol table
 - ExitScope()
 - Changes the current-level symbol table pointer so that it points to the symbol table of surrounding scope
- Use a global symbol table pointer to keep track of the current scope

Linear IR

- Low level IL before final code generation
 - A linear sequence of low-level instructions
 - Implemented as a collection (table or list) of tuples
- Similar to assembly code for an abstract machine
 - Explicit conditional branches and goto jumps
- Reflect instruction sets of the target machine
 - Stack-machine code and three-address code

Stack-machine code two-address code three-address code Push 2 **t1**

MOV 2 => t1
MOV y => t2
MULT t2 => t1
MOV x => t4
SUB t1 => t4

t1 :=	2
t2 :=	У
t3 :=	t1*t2
t4 :=	Χ
t5 :=	t4-t3

Linear IR for x - 2 * y

Stack-machine code

Also called one-address code

- Assumes an operand stack
- Take operands from top of stack; push results onto the stack
- Need special operations such as
 - Swapping two operands on top of the stack
- Compact in space, simple to generate and execute
 - Most operands do not need names
 - Results are transitory unless explicitly moved to memory
- Used as IR for Smalltalk and Java

```
Stack-machine code for x – 2 * y
```

Push 2 Push v Multiply Push x subtract

Three address code

- Each instruction contains at most two operands and one result.
- Typical forms include
 - Arithmetic operations: x := y op z | x := op y
 - Data movement: x := y [z] | x[z] := y | x := y
 - Control flow: if y op z goto x | goto x
 - Function call: param x | return y | call foo
- Each instruction maps to at most a few machine instructions
- Additional constraints depend on target machine instructions
 - Eg., for x := y op z and x := op y
 - all operands must be in registers \rightarrow all operands must be temporaries?
- Reasonably compact, while allowing reuse of names and values

Three-address code for x - 2 * y

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Storing Three-Address Code

- Store all instructions in a quadruple table
 - Every instruction has four fields: op, arg1, arg2, result
 - The label of instructions → index of instruction in table

Three-address code

Quadruple entries

	ор	arg1	arg2	result
(0)	Uminus	С		t1
(1)	Mult	b	t1	t2
(2)	Uminus	С		t3
(3)	Mult	b	t3	t4
(4)	Plus	t2	t4	t5
(5)	Assign	t5		а

Alternative: store all the instructions in a singly/doubly linked list What is the tradeoff? cs5363 15

Mapping Storages To Variables

Variables are placeholders for values

- Every variable must have a location to store its value Register, stack, heap, static storage
- Values need to be loaded into registers before operation

x and y are in registers x and y are in memory

Three-address code for x - 2 * y:

t1	:= 2	
t2	:= t1*y	
t3	:= x-t2	

Which variables can be kept in registers? Which variables must be stored in memory?

Appendix: Control-flow graph

Graphical representation of runtime control-flow paths

- Nodes of graph: basic blocks (straight-line computations)
- Edges of graph: flows of control
- Useful for collecting information about computation
 - Detect loops, remove redundant computations, register allocation, instruction scheduling...
- Alternative CFG: Each node contains a single statement



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Appendix: Dependence graph

- Graphical representation of reordering constraints between statements
 - Each node n is a single operation/statement
 - Edge (n1,n2) indicates n2 uses result of n1
 - The order of evaluating n1,n2 cannot be reversed
 - Graph is acyclic within each basic block; is cyclic if loops exist
- Used in reordering transformations
 - Instruction scheduling, loop transformations
- Construction
 - For each pair of statements, evaluate ordering constraint



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Appendix: Static Single-Assignment

- A variable can hold multiple values throughout its lifetime
 - Mapping multiple values to a name can hide opportunities of optimization
- Static single-assignment form (SSA)
 - Each variable is defined by a single operation in the code
 - Each use of variable refers to a single definition
 - Use Ø-functions to merge definitions from different control-flow paths

$$\begin{array}{c} x:=...\\ y:=...\\ while (x < 100)\\ x:=x+1\\ y:=y+x \end{array}$$
 SSA:
$$\begin{array}{c} x0:=...\\ y0:=...\\ if (x0 < 100) \text{ goto loop}\\ goto next\\ loop: x1:= \oslash(x0,x2)\\ y1:= \oslash(y0,y2)\\ x2:=x1+1\\ y2:=y1+x2\\ if (x2 < 100) \text{ goto loop}\\ next: x3:= \oslash(x0,x2)\\ y3:= \oslash(y0,y2) \end{array}$$