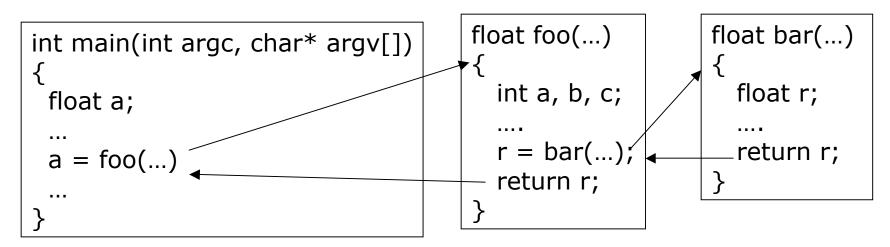
Procedure and Object-Oriented Abstraction

Scope and storage management

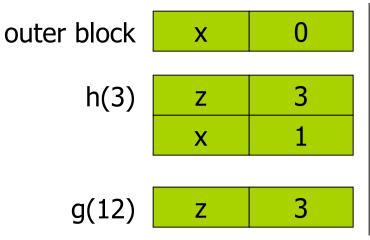
Procedure abstractions

- Procedures are fundamental programming abstractions
 - They are used to support dynamically nested blocks
 - Paired function call and return jumps
 - They have standalone semantics defined by an abstraction interface
 - input parameters, return values, global side effects
- Procedures are units of separate compilation
 - They represent parameterized blocks of computation



Scoping rules

Global and local variables

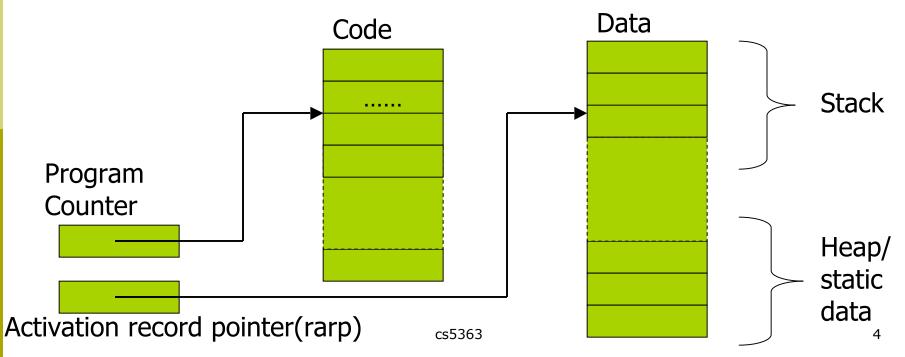


program main(input,output); var x : integer; function g(z: integer) : integer; begin g := x+z end; function h(z: integer) : integer; var x : integer; begin x := 1; h:=g(z) end; begin x := 0; print(h(3)) end

- Static scoping
 - Find global variables in enclosing blocks in program text
- Dynamic scoping
 - Find global variables in the most recently evaluated blocks
 - Easier to implement in interpreted languages
- What is the scoping rule for C/C++, Java?

Simplified memory model

- Runtime stack: activation records of blocks/functions
 - Block entry: add new data to stack
 - Block exit: remove outdated data
- Heap: data of varying lifetime
 - Variables that last throughout the program
 - Address may be contained by variables on the runtime stack



Managing Data Storage

- Local variables --- activation records on stack
 - Declared inside a block (e.g. function body)
 - Enter block: allocate space
 - Exit block: de-allocate space
 - Local variables in an enclosing block
 - Already allocated before entering current Block
 - Remain allocated after exiting current block
 - Function parameters and return value
 - Allocated and initialized before entering function body
 - Formal parameters dallocated after exiting function body
- Global/static variables --- static data areas
 - Allocated when program is loaded to memory
 - Storage remain until program exits
- Dynamically allocated variables --- heap
 - Storage dynamically allocated at runtime (e.g., malloc in C)
 - Storage remain until explicitly de-allocated or garbage collected

Activation Record

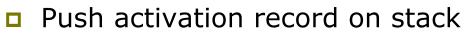
Allocate storage for each block dynamically

- Allocate an activation record before evaluating each block
 - Storage for each local variable determined as compile time
 - Values of local variables evaluated at runtime
- Delete the activation record after block exits

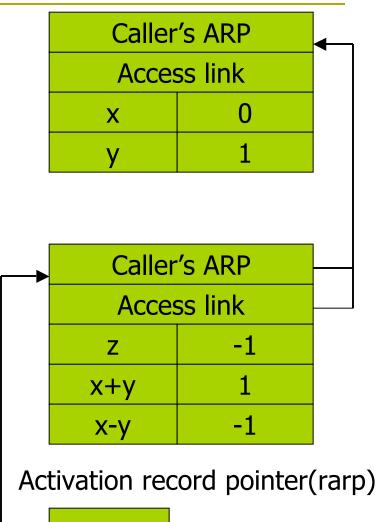
Allocate AR with space for x, y Set values of x, y Allocate AR for inner block Set value of z Delete AR for inner block Delete AR for outer block

May need space for intermediate results such as (x+y), (x-y)

Activation Records For Inline Blocks

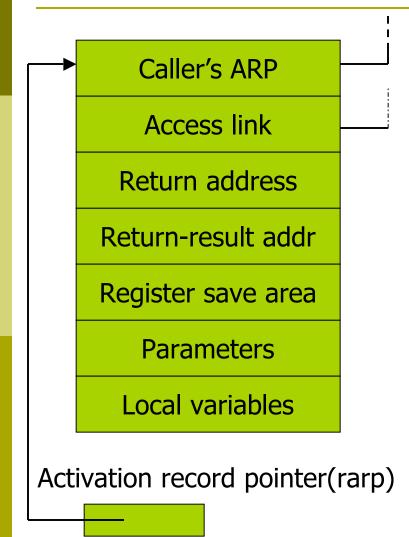


- Set caller ARP to rarp
- Set rarp to new AR
- Pop activation record off stack
 - Reset rarp to caller's ARP
- When making function calls
 - Caller must also set return address, return value addr, saved registers, and parameters



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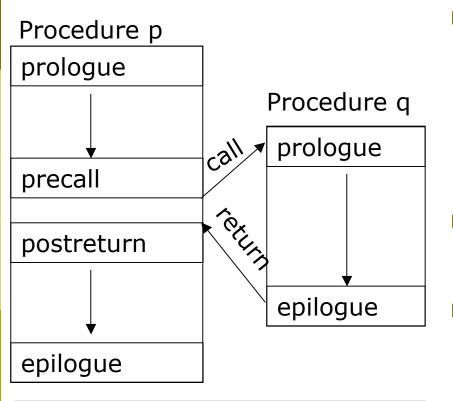
Activation Records For Procedures



Access link

- Pointer to activation record of the enclosing block
- Return address
 - Pointer to the instruction immediately following function call
- Return-result address
 - Address of the storage to put the result to be returned
- Register save area
 - Save register values before function call
 - Restore register values before return
- Parameters
 - Storage for function parameters
 - Values initialized by caller

Linkage Convention: Implementing Function Calls



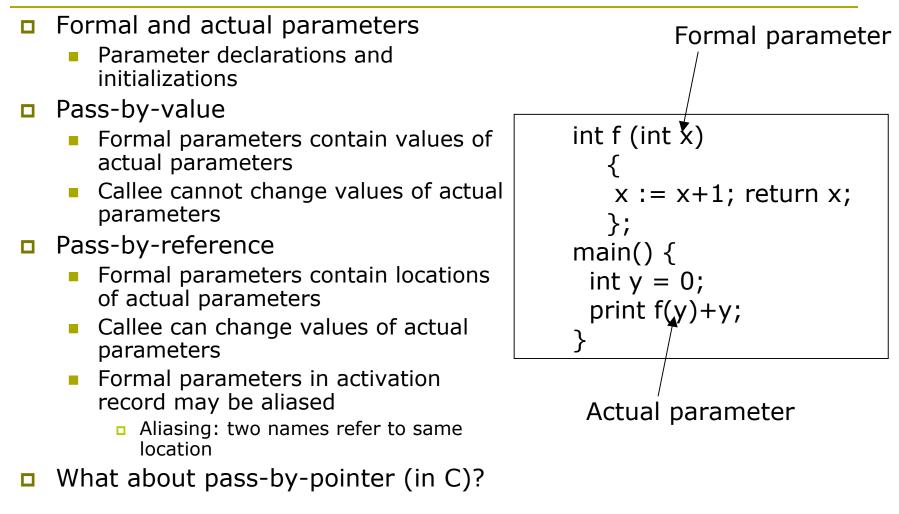
Linkage convention: programs in different files must follow a single contract of function call implementation Precall

- Push callee's AR (increment rarp)
- Set caller's ARP
- Set return address
- Set return result addr
- Save live register values
- initialize formal parameters
- Postreturn
 - Restore live register values
 - Pop callee's AR(decrement rarp)
- Prologue
 - Initialize local variables
 - Load local environment (access link)
- Epilogue

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- Deallocate local variables
- Goto return address

Parameter Passing



Example: What is the final result?

pseudo-code



```
int f (int x)
```

```
{
x := x+1; return x;
```

```
};
main() {
```

int y = 0;
print f(y)+y;
}



- Draw the activation records for the evaluation
- What parameter passing is supported by the languages you know?

Exercise: Managing Function Calls

- 1: program main(input,output)
- 2: var x : integar;
- 3: function f(y : integer)
- 4: begin

5:
$$f = (x + y) - 2$$

- 6: end
- 7: function g(function h(b:integer):integer)
- 8: begin
- 9: var x : integer;
- 10: x := 7;
- 11: g = h(x);
- 12: end
- 13: begin
- 14: x := 5;
- 15: g(f);
- 16: end

Accessing Variables In Memory

Each memory store has an address

- Base address: the starting address of a data area
 - Local variables of current block activation record pointer (rarp)
- Offset: the number of bytes after the base address
 - Local variables of current block
 predetermined at compile time

Address of variable

base address + offset

Accessing local variable a:

LoadAI rarp, @a => r1

loadI @a => r1 loadA0 rarp, r1 => r2

loadI @a => r1 Add rarp, r1 => r2 load r2 => r3

Accessing Global/Static Variables

Allocated separately in static data area

- Base address unknown until program is loaded into memory
 - Use symbolic labels to substitute at compile time
 - Symbolic labels replaced with runtime value by assembler and loader
- Offset calculated at compile time
 - Individual variables: offset=0
 - Group of data
 - layout pre-determined

Accessing global variable fee:

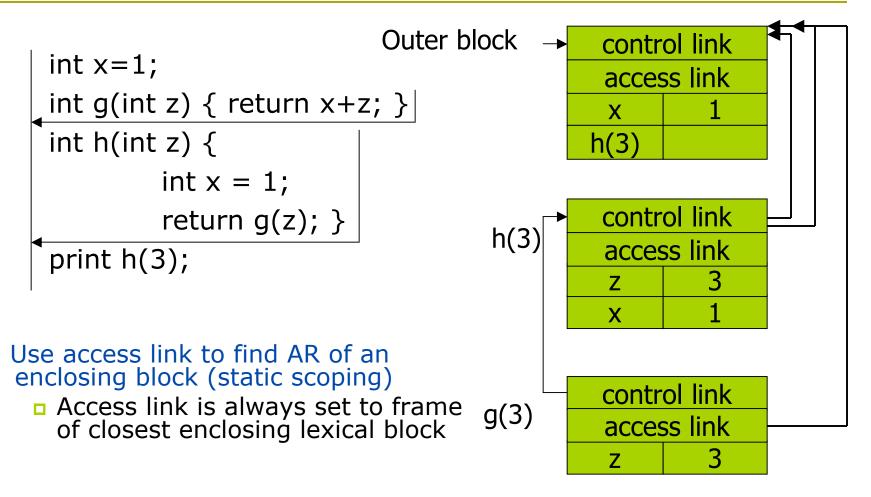
LoadI &fee => r1 Load r1 => r2

Accessing foo.a:

LoadI &foo => r1 LoadAI r1, @foo_a => r3

LoadI &foo => r1 Add r1, @foo_a => r2 Load r2 => r3

Variables of Enclosing Blocks



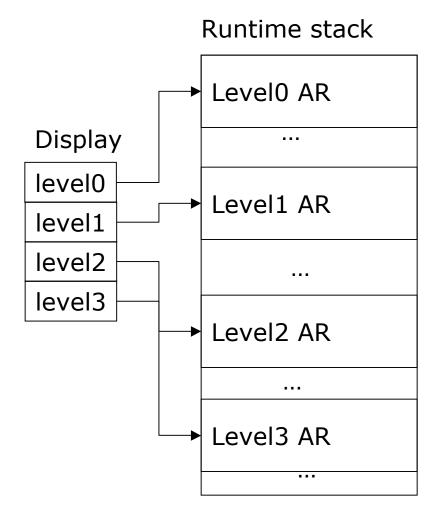
Coordinates of Variables

- Accessing local variables Offset calculated at compile time Need to find the base address The AR that contains the variable Lexical level of a block Number of enclosing scopes g: 1; h: 1; outer-block: 0 For each variable x Coordinate of x is <n, o>, where n: lexical level of block that defines x • O: offset of x in it's AR If a block at lexical level m references x
 - Follow access link m-n times to find the base address for x

int x=1; int g(int z) { return \mathbf{x} +z; } int h(int z) { int x = 1; return $g(z); \}$ print h(3); Coordinate for x: <0,8> Lexical level of g: 1 Load instructions: loadAI rarp, 4 => r1loadAI r1, 8 => r2

Global Display

- Allocate a global array (global display)
 - hold the address of most recent ARs at each lexical level
 - When pushing a new AR, save the previous AR at the same lexical level, modify global display
 - When popping an AR, restore the global display with saved AR at the current lexical level
- To access variable <n,o>
 - use the ARP at element n of the global display



Global Display vs. Access Links

Maintenance

- Constant cost for global display
 - When entering every block at lexical level n, save the level-n ARP from global display, replace it with new ARP
 - When exiting the block, restore the old level-n ARP into display
- Varying cost for access links
 - If a level-m block invokes a level-n block
 - $m==n-1 \rightarrow$ callee's access link points to caller's AR
 - $m==n \rightarrow callee's access link = caller's access link$
 - $m > n \rightarrow$ callee's access link = caller's level (n-1) access link
- Referencing variables in enclosing scope
 - Constant cost through global display
 - Varying cost through access links
- The tradeoff depends on the ratio of non-local references
- □ If ARs can outlive their invocation, access link must be used
 - The chosen approach by functional programming languages

Managing memory

Registers

- Data need to be loaded to registers before being operated on
- If a variable can be kept in register throughout its lifetime, it does not need a storage
- Register-to-register model
 - Try to keep as many variables in registers as possible
 - Allocate memory storage later if not enough register

Alignment and padding

- Target machines may restrain where data can be stored
 Needs to be at 32/64 bit boundaries, etc.
- Cache and variable layout
 - Data in memory can be loaded into cache and reused
- Managing the heap: dynamically allocate/free storage

Object-Orientation

- Abstraction: information hiding
 - Separate interface and implementation details
 - Function and data abstractions
- Object-oriented programming
 - Organize concepts into objects and classes
 - Build extensible systems
- Language concepts
 - Encapsulation (access control): members can be private
 only a few functions can access private data
 - Dynamic lookup definitions of functions (function pointers)
 Object behavior can change dynamically
 - Subtyping polymorphism (relations between types)
 Operations can be applied to multiple types of values
 - Inheritance (reuse of implementation)
 Subclasses can modify and inherit behavior of base classes

Static vs. dynamic lookup

- What about operator overloading (ad hoc polymorphism)? int add(int x, int y) { return x + y; } float add(float x, float y) { return x + y; }
 - Static lookup: overloading is resolved at compile time
 - Examples: C++ non-virtual functions, Java static functions
- Dynamic lookup: resolved at run time
 - C++ virtual functions, Java non-static functions
 - Difference: flexibility vs. efficiency

```
class vehicle {
   protected: double speed, fuel;
   public: virtual void run() = 0;
};
class car : public vehicle {
   public: virtual void run() { if (fuel > 0) fuel = fuel - 1;}
};
vehicle* a = new car; a->run();
```

Static Binding of Methods

C++ class: non-virtual member functions

 Essentially global functions with an extra object pointer parameter

```
class vehicle {
```

```
protected: double speed, fuel;
public: vehicle() : speed(0),fuel(0) {}
      void start(double x) {speed = x;}
```

```
};
vehicle* a = new vehicle; a->start(5);
```

```
Java/C++: Static Methods/Variables
```

Essentially global functions/variables in a name space

```
A single instance of member for all class objects 
class vehicle {
```

```
static protected double speed, fuel;
```

```
public static void start(double x) {speed = x;}
```

```
};
Vehicle::start(3.0);
```

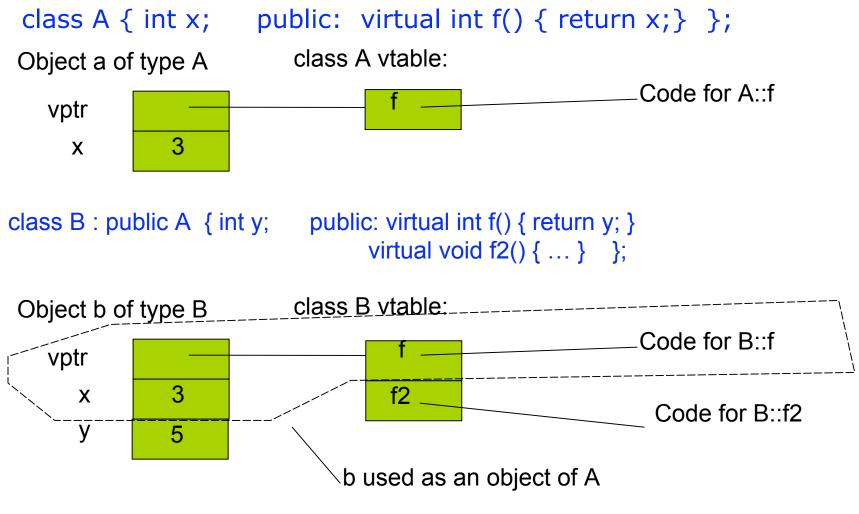
Implementing Dynamic Objects

An object consists of

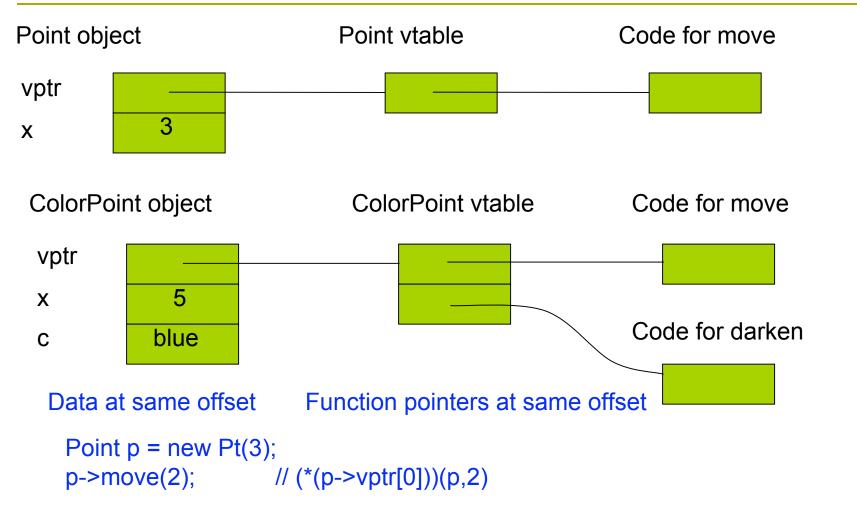
- Hidden data
 - instance variables, also called member data
 - hidden functions also possible
- Public operations
 - methods or member functions
 - can also have public variables in some languages
- Dynamic binding
 - Put all the name-value bindings into a table
 - Table can be changed, just like the activation record of a function
- Example: the vehecle/car objects
- Object-oriented program:
 - Send messages to objects

hidden data	
msg1	method1
msgn	methodn

C++: Object Layout and Single Inheritance



Looking up methods



C++ method lookup

C++ compiler knows all the base classes

- Offset of data and function pointer are same in subclass and base class
- Offset of data and function pointer known at compile time
- Code p->move(x) compiles to equivalent of (*(p->vptr[move_offset]))(p,x)

Exercise: OO Memory Layout

Draw the memory layout for the following C++ code immediately before the main function returns.

> class A { int x; public: virtual void f(); }; class B: public A { int y; public: virtual void f(); }; class C: public B { int z; public: virtual void g(); }; int main() { C *pc = new C; B *pb = pc; A *pa = pc; }